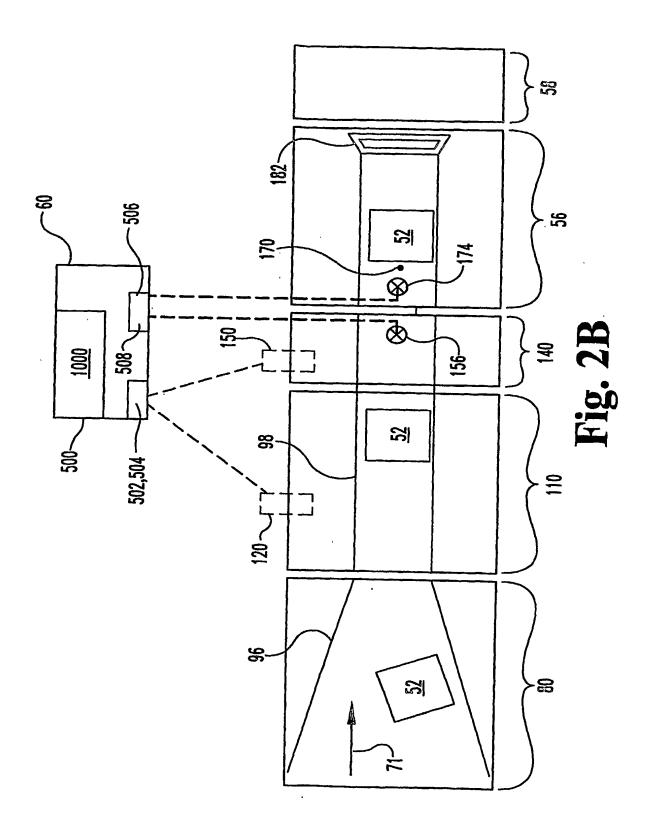
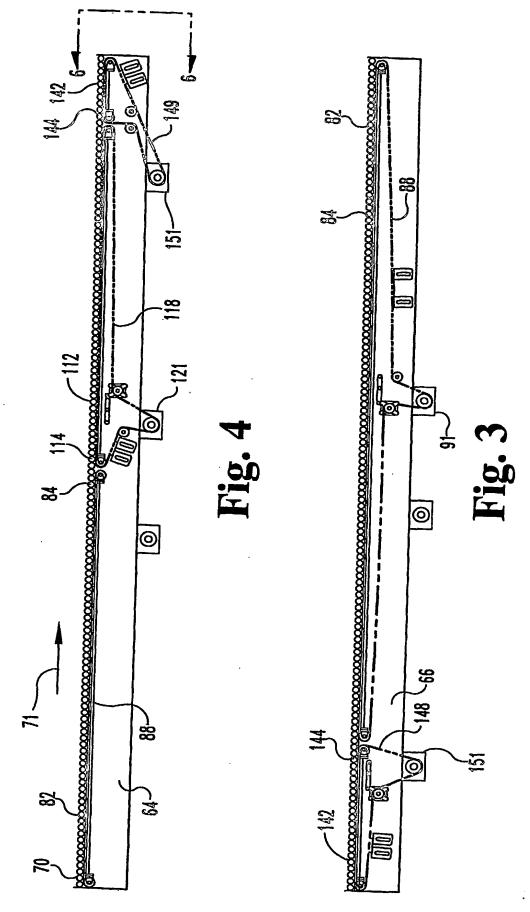


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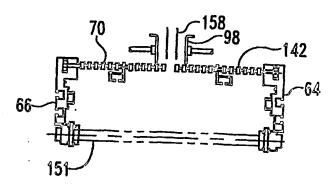


Fig. 6

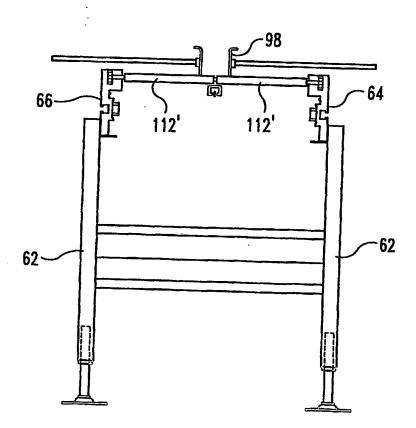
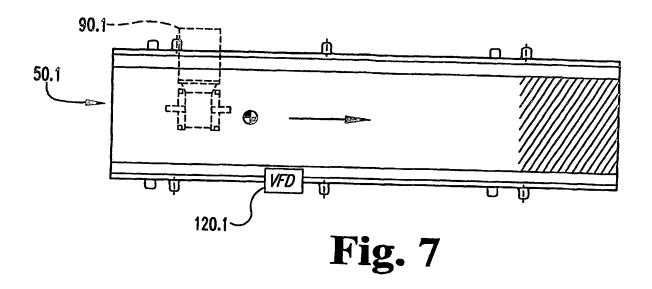
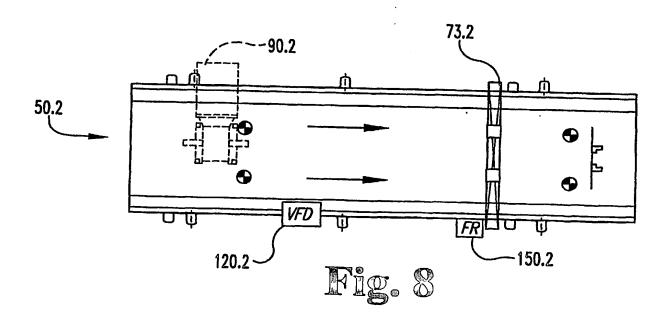
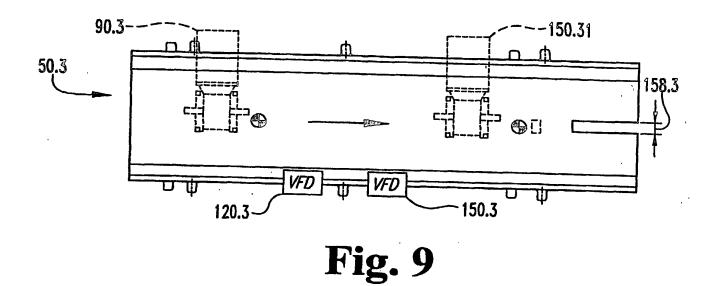
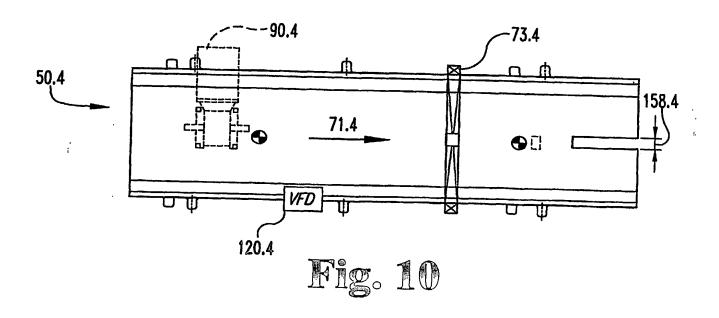


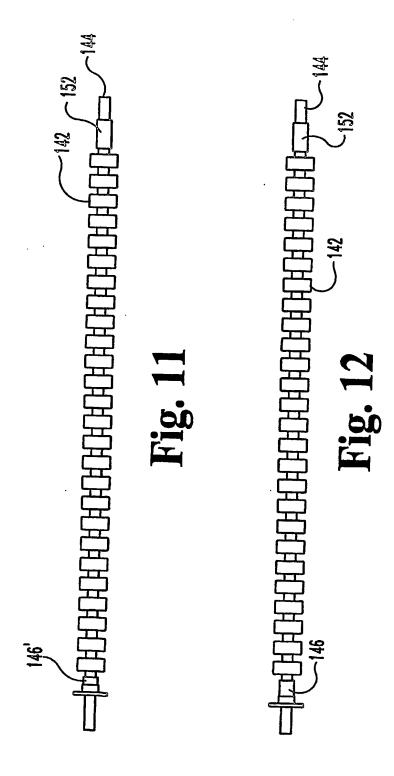
Fig. 5











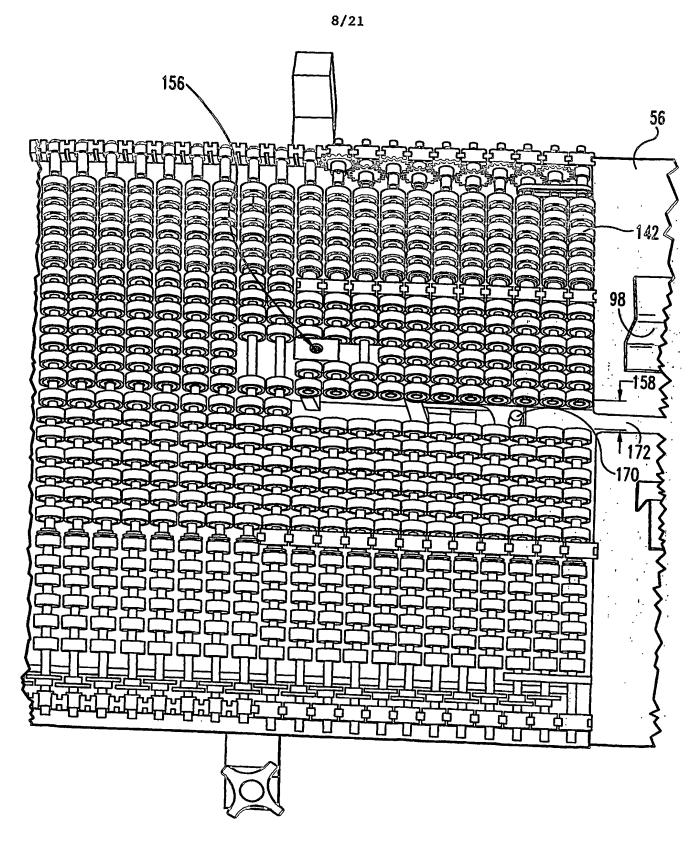
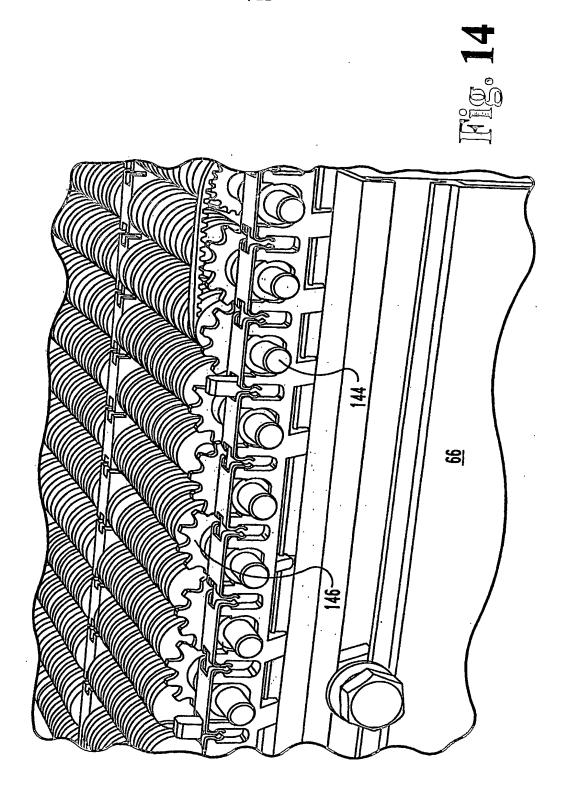
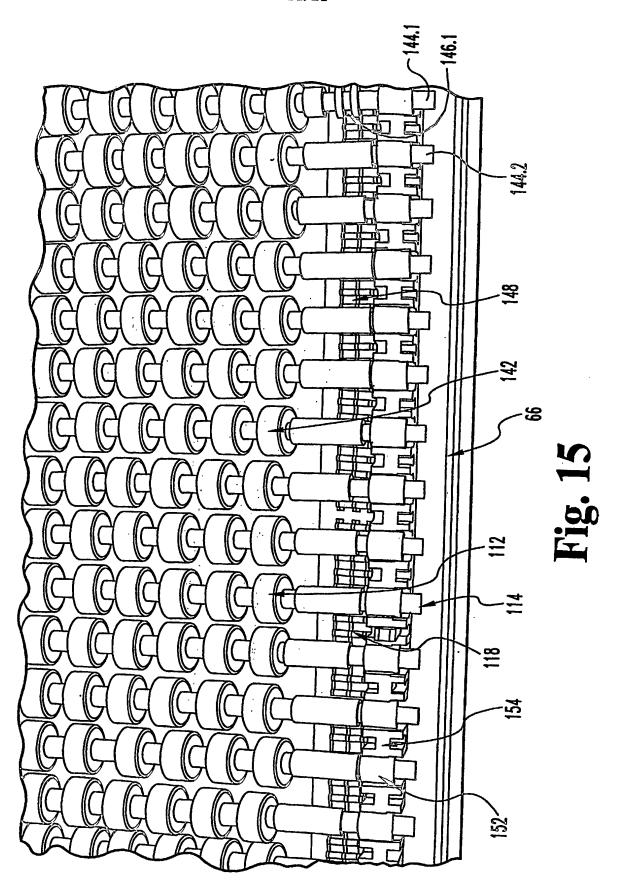


Fig. 13





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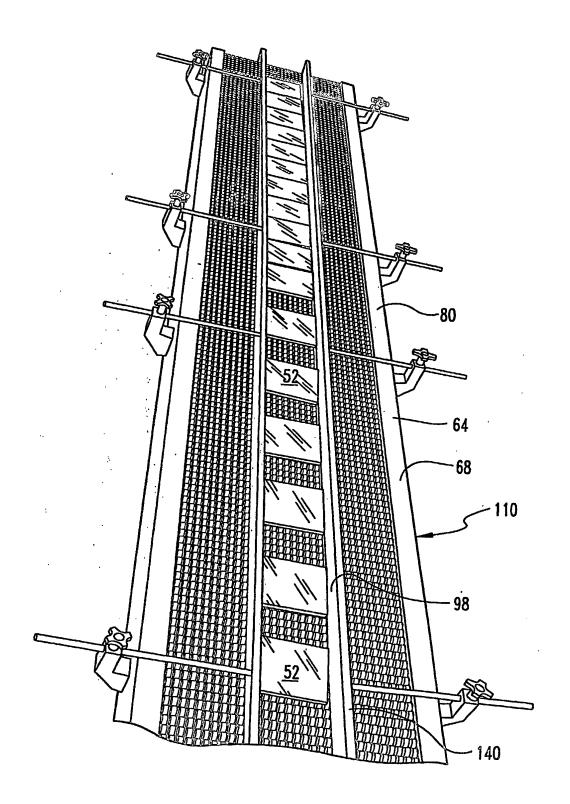
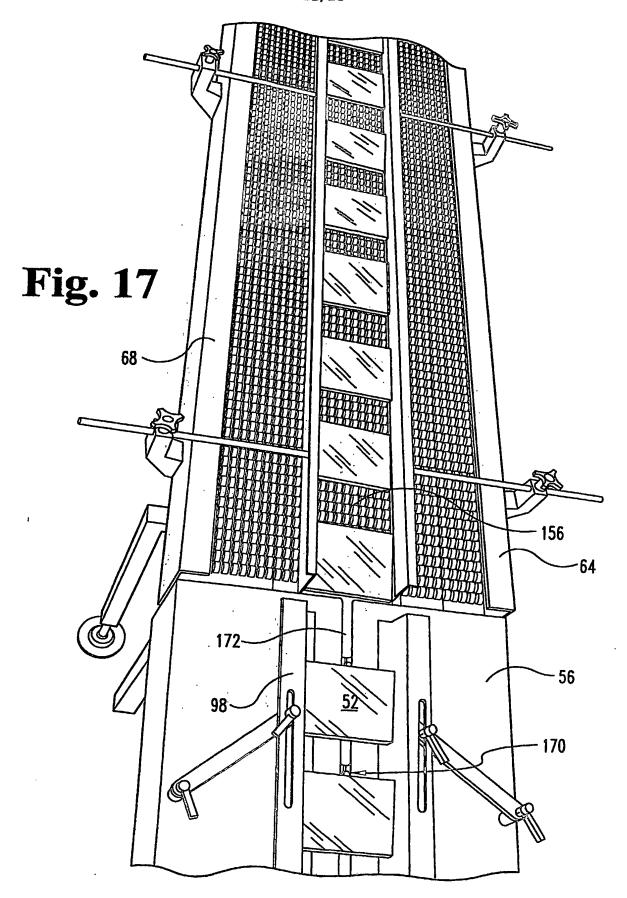
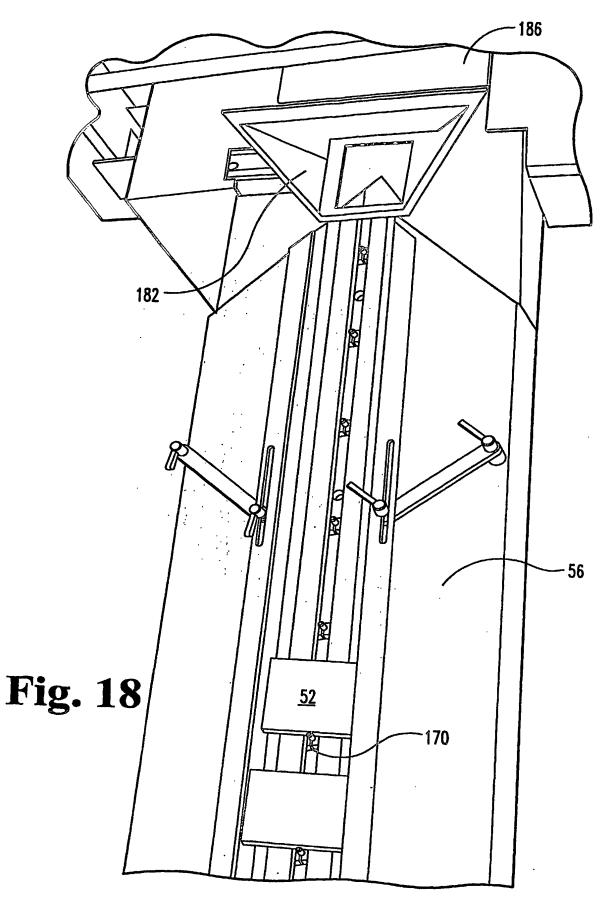


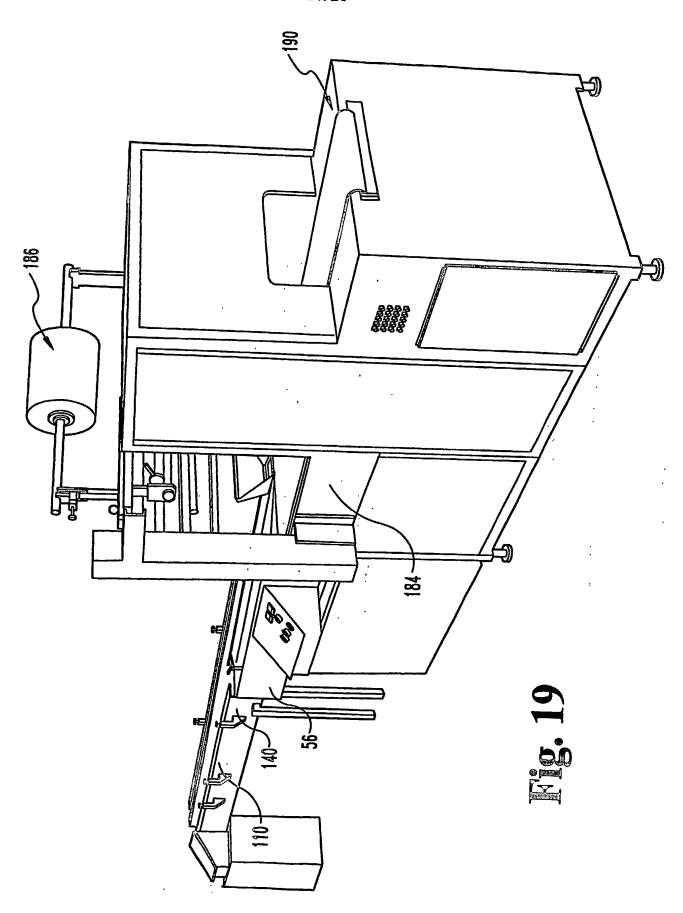
Fig. 16



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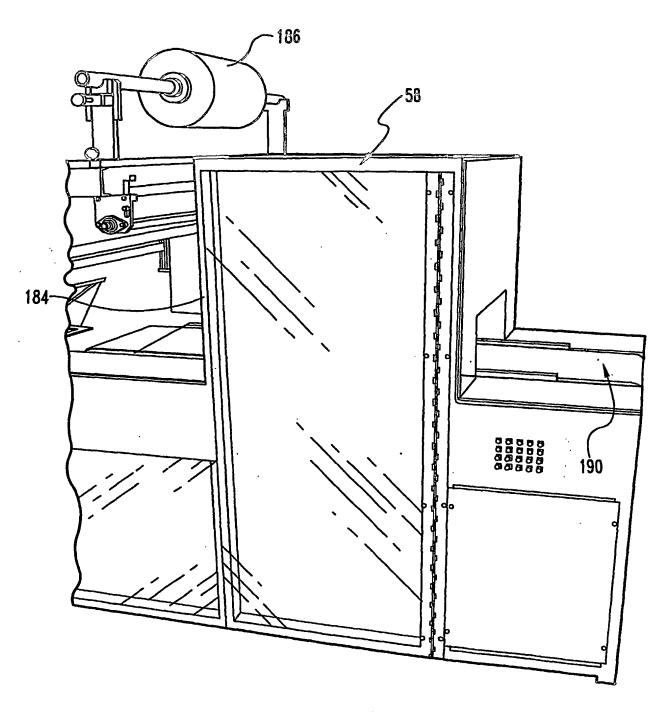
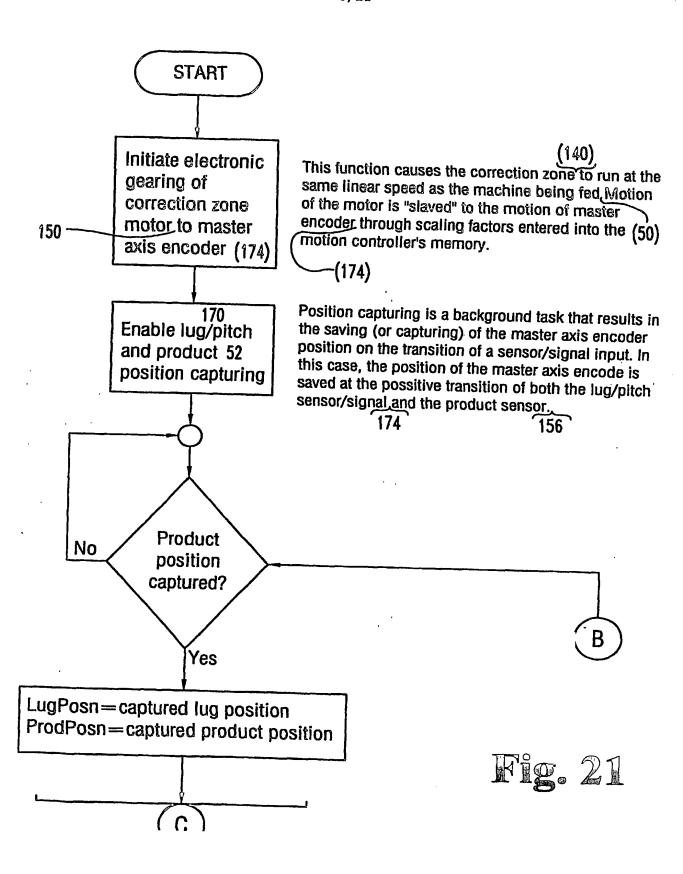


Fig. 20



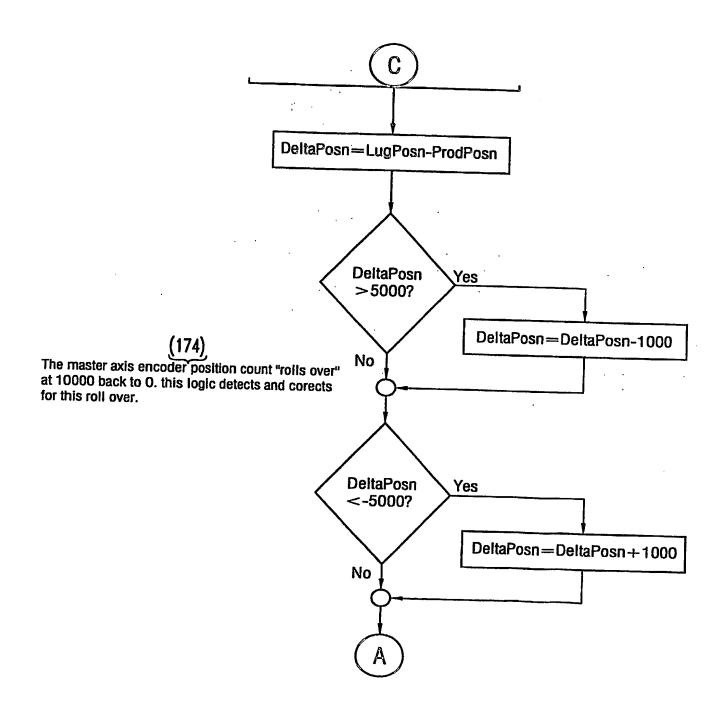
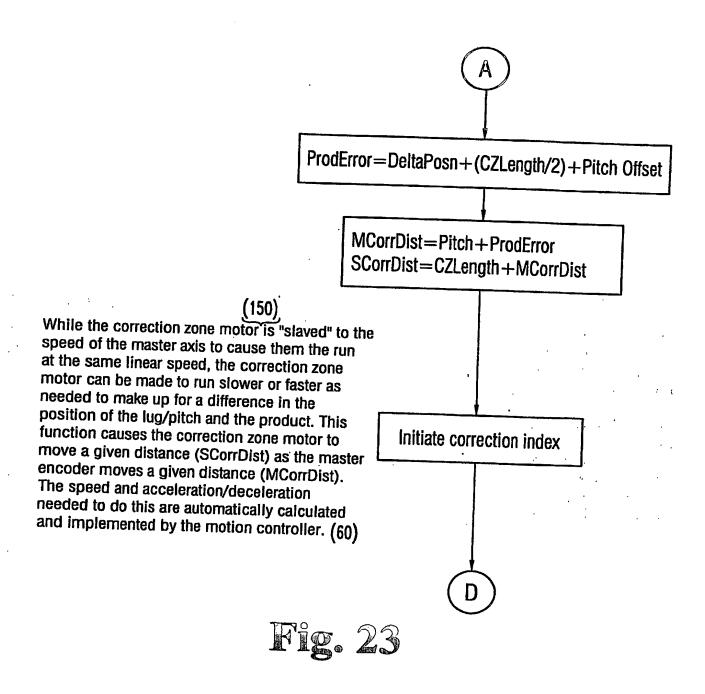


Fig. 22



position capture Reset product The lug/pitch position capture trigger is automatically Whenever a position capture is triggered, the trigger sensor/signal. The product postion capture trigger must be reset before another capture can occur. reset on the negative transition to the lug/pitch s programmatically reset here.



Pitch: Distance between lugs/pitch marks (in inches) entered via the OPI, Lugposn: Position (in encoder counts) of the lug/pitch mark. ProdPosn: Position (in encoder counts) of the product.

CZLength:. Correction zone length (in inches) entered via the OPI,

Variable Description

JeltaPosn: Difference between LugPosn and ProdPosn. Distance (in inches) that the product leads/lags the lug/pitch mark.

ProdError: Product position error. Distance (in inches) that the product needs to be advanced/retarded so that it can match the position of the lug/pitch mark.

change the apparent position of the Lug/pitch mark sensor/signal instead of changing its PitchOffset: Manual lug/pitch mark adjustment factor (in inches) entered via the OPI. Can be used to actual physical position.

McorrDist: Master correction distance. Master axis encoder distance remaining to be used to make the ScorrDist: Slave correction distance. Correction zone motor distance moved during a correction index. correction index.

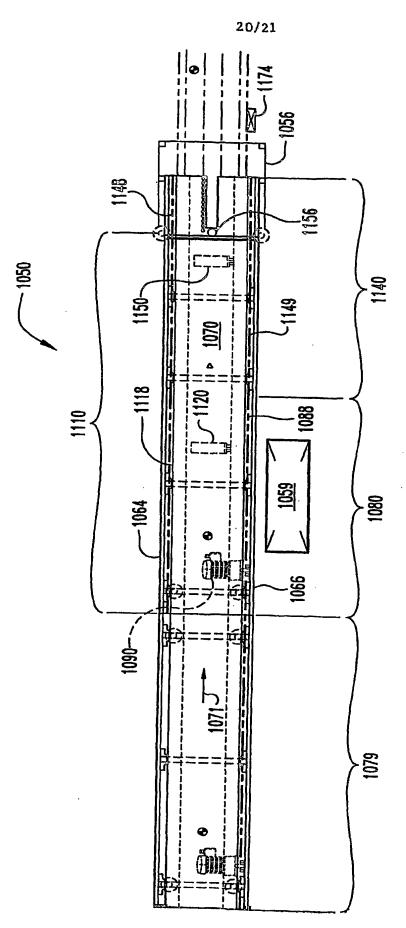


Fig. 25

